



**Maude Gondré**  
**Institute of Radiation Physics**

# **Physics of radiation therapy**

**Imaging in radiotherapy  
and advanced treatment  
techniques**

*Unil*

**UNIL** | Université de Lausanne

**CHUV**

# Outline

## Introduction to image guided radiotherapy (IGRT)

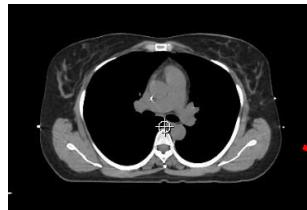
*Basic principles*

*Reference and day imaging*

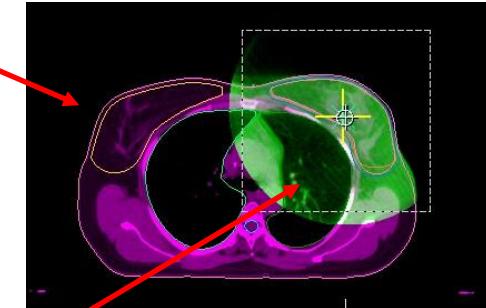
*Practical example: CyberKnife*

# Basic principles

D0: reference image



Planning CT (reference)



D1: first treatment session

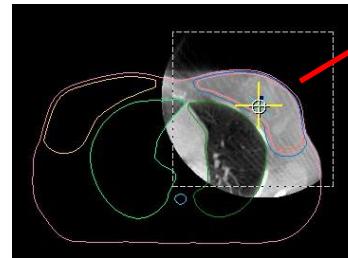
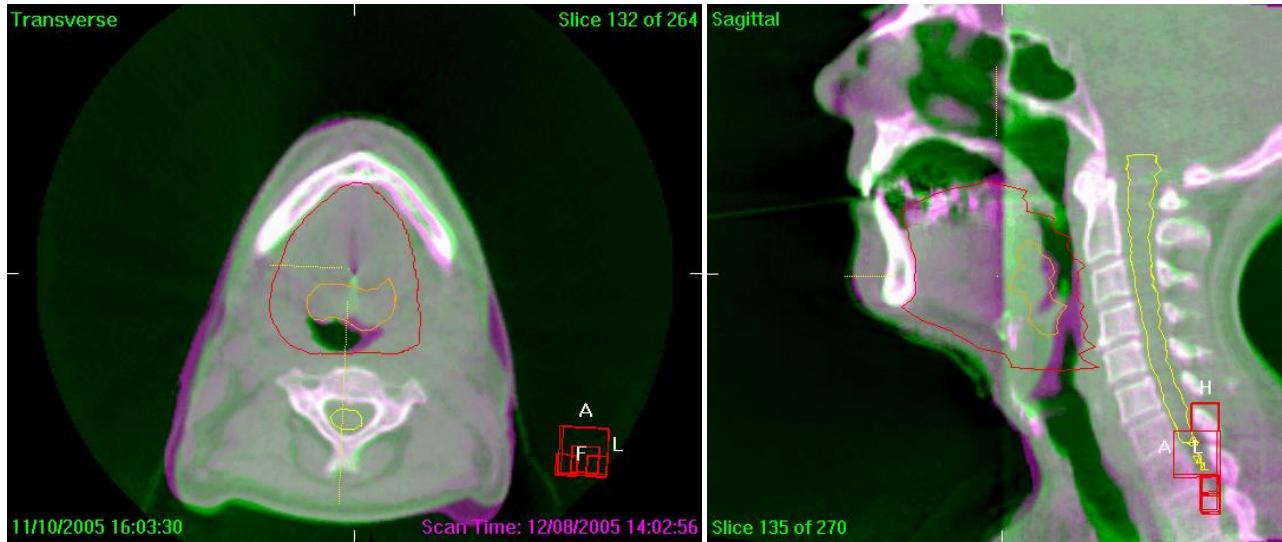
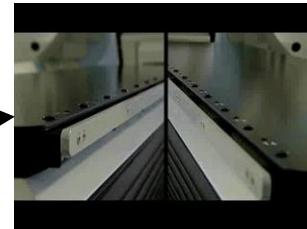


Image of the day (IGRT)

# Registration



Position Error	
Translation (cm)	
X	-0.25
Y	-0.05
Z	0.24
Rotation (dg)	
X	360.0
Y	2.5
Z	1.8



# Reference imaging

# Reference imaging



CT scan:

*Define reproducible position of the patient for the treatment*

*Use for the treatment planning in the TPS*

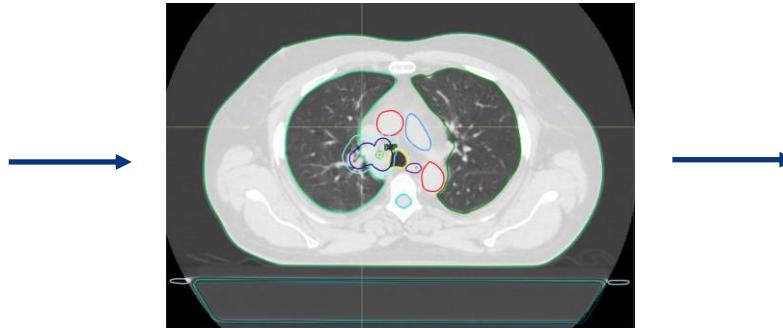
*Use as reference image for registration before the treatment*



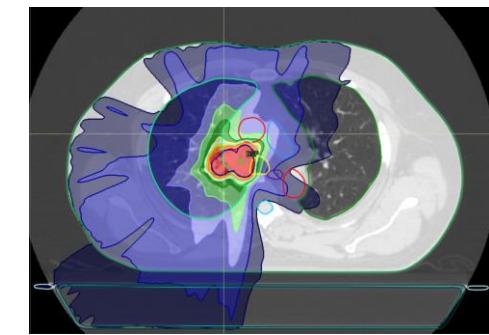
# Reference imaging



Planning CT

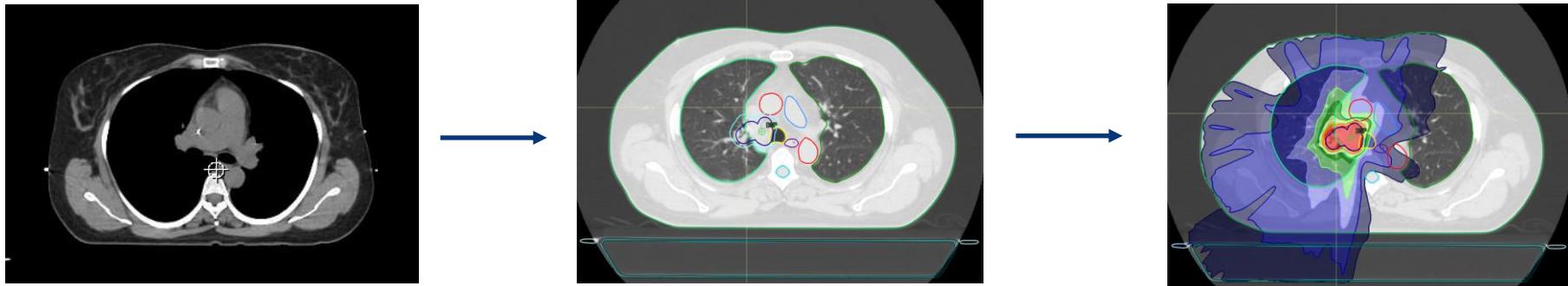


Contours delineation  
(physician)

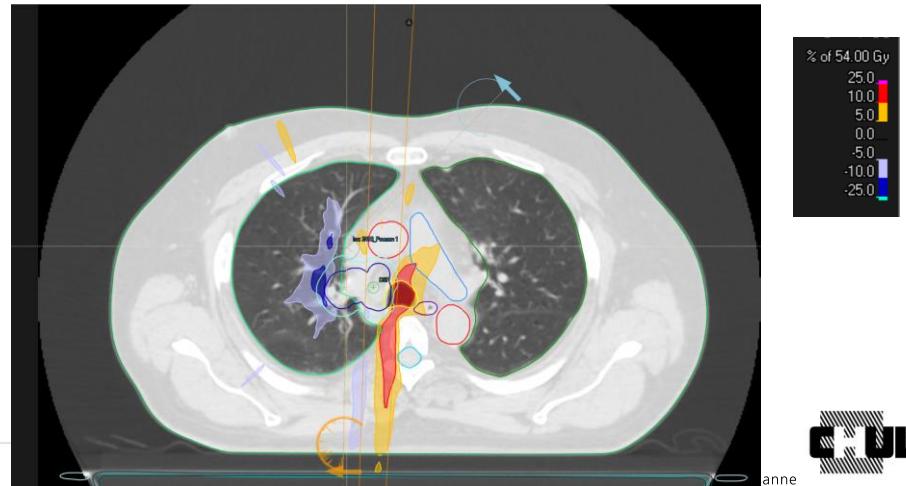
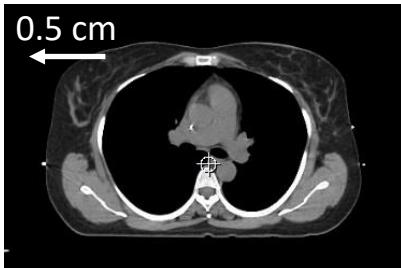


Planification  
(medical physicist)

# Reference imaging

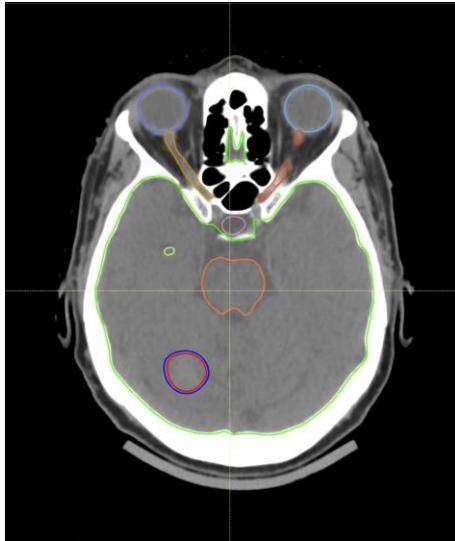


What is the impact of a 0.5 cm right displacement?



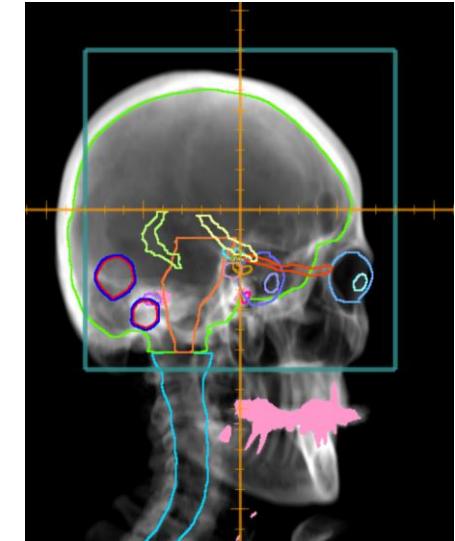
# Reference imaging

## Digitally reconstructed radiograph (DRR)



CT (3D)

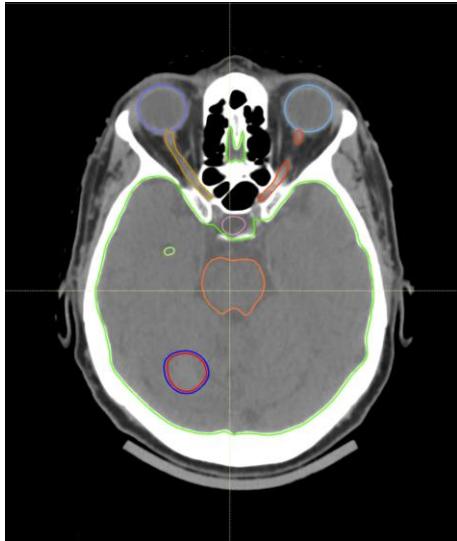
?



DRR (2D)

# Reference imaging

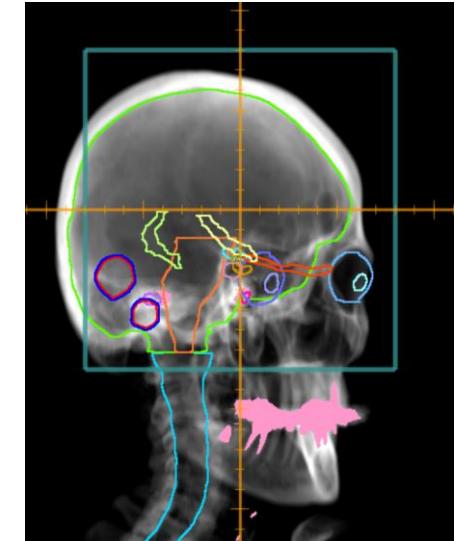
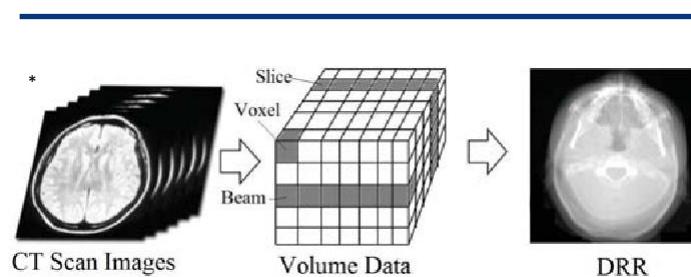
## Digitally reconstructed radiograph (DRR)



CT (3D)

$$I = I_0 e^{-(\mu_1 x_1 + \dots + \mu_n x_n)}$$

$\mu$  = linear attenuation coefficient



DRR (2D)

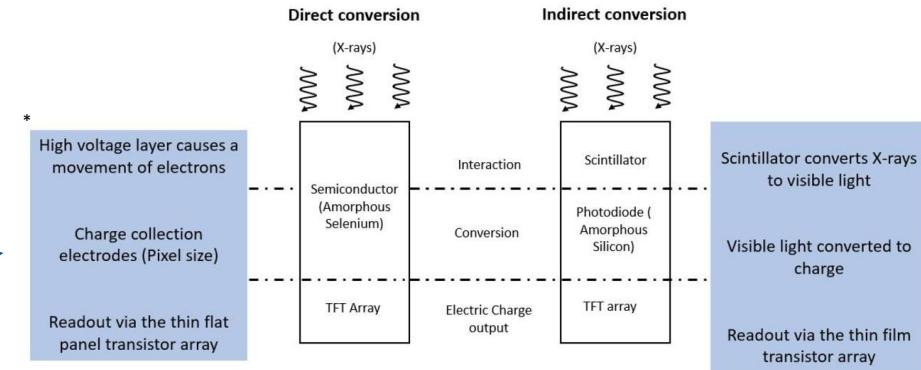
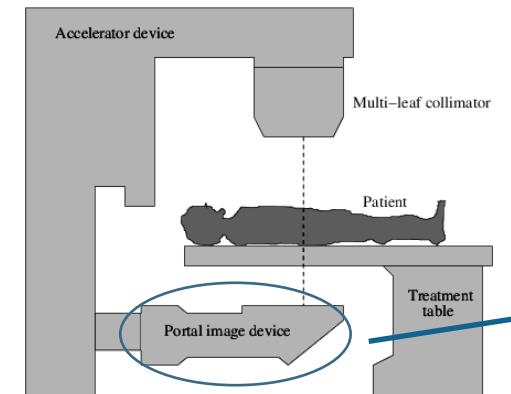
# Day imaging

# Portal imaging

Images obtained with treatment beam (MV energy range)

More X-rays at the detector = less absorption in the body = less dense tissue

$$I = I_0 e^{-\mu x}$$



<https://www.twi-global.com/technical-knowledge/faqs/digital-radiography>

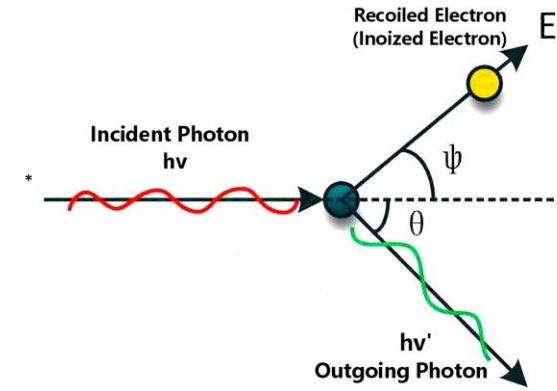
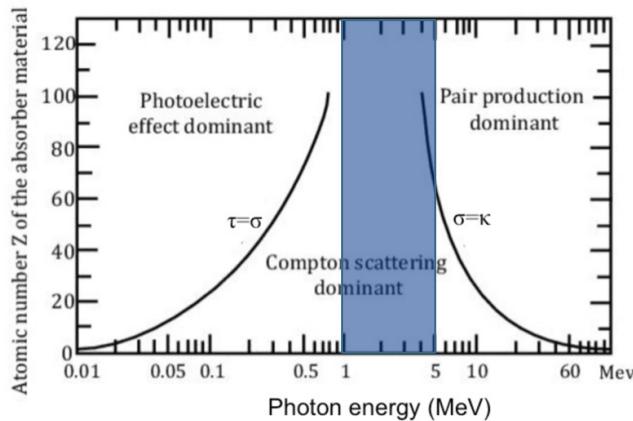
# Portal imaging

MV beam → Compton scattering dominant

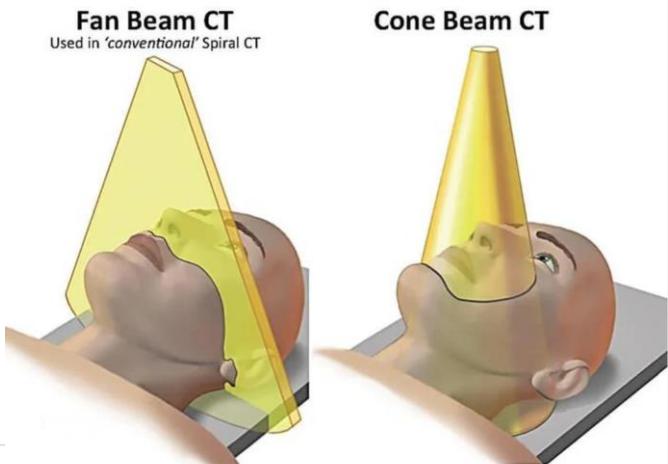
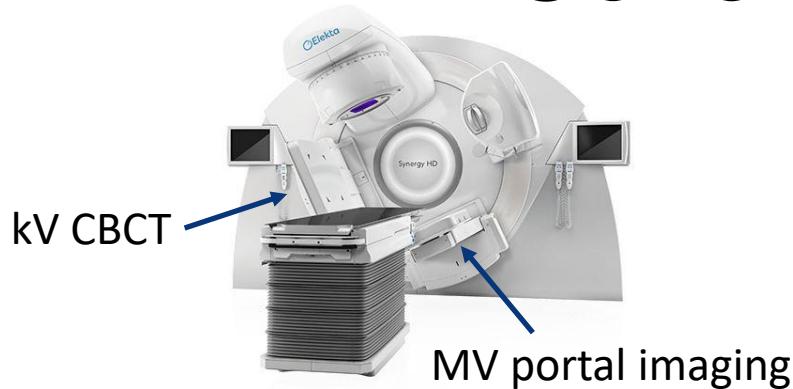
Scattered photons = loss of information

- $\neq$  energy =  $\neq$  tissue density
- $\neq$  direction =  $\neq$  localisation of tissue

} loss of image quality



# Cone beam CT



## CBCT

100-120 kV energy → better image quality than portal imaging

Cone beam shape (1 rotation):

- More scatter than conventional CT
- Less dose than conventional CT

# CBCT

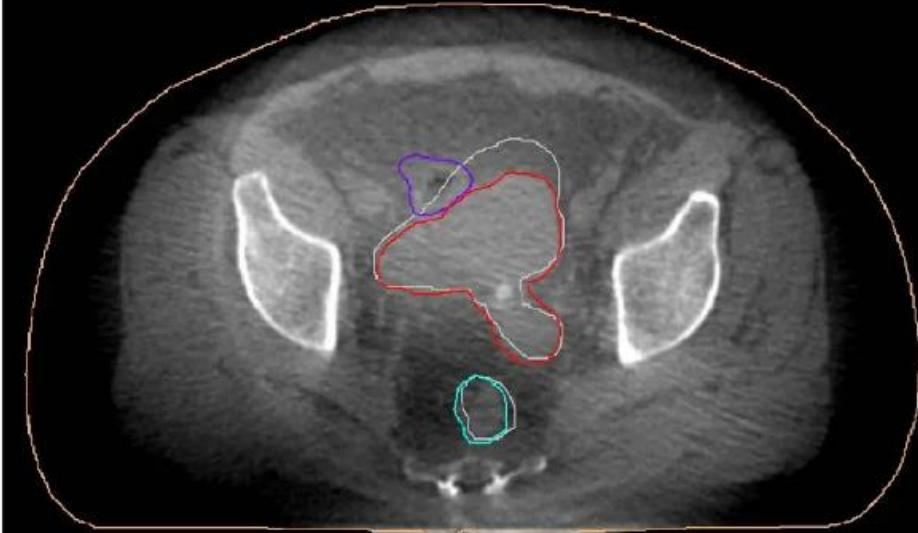
Planning-CT



CTV

Rectum

CBCT



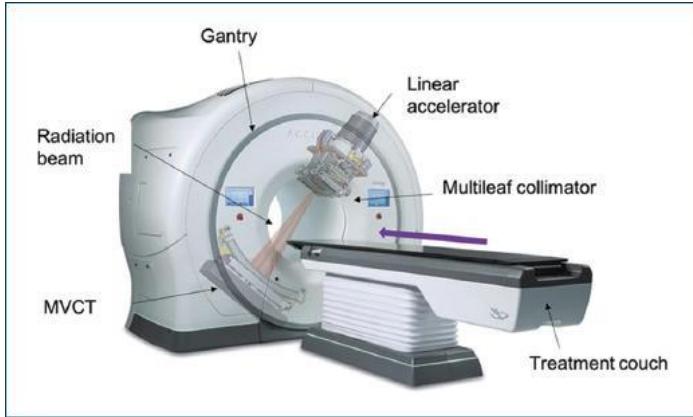
CTV

Rectum

Bowel

Planning-CT  
contours

# Megavoltage CT

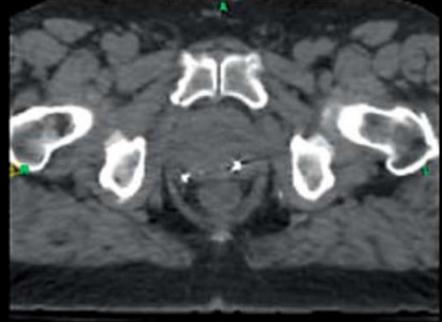


MVCT

Tomotherapy/Radixact (Accuray)  
3.5 MV fan-beam

Patient images: prostate

Diagnostic kVCT

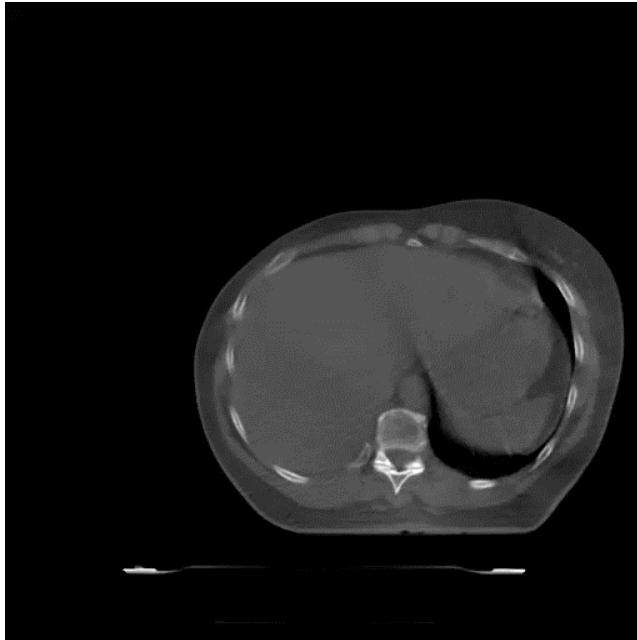


Tomotherapy MVCT



\*Kupelian, Patrick & Langen, Katja. (2011). Helical Tomotherapy: Image-Guided and Adaptive Radiotherapy. *Frontiers of radiation therapy and oncology*. 43. 165-80. 10.1159/000322420.

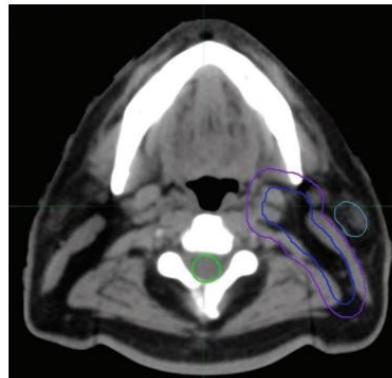
# kVCT



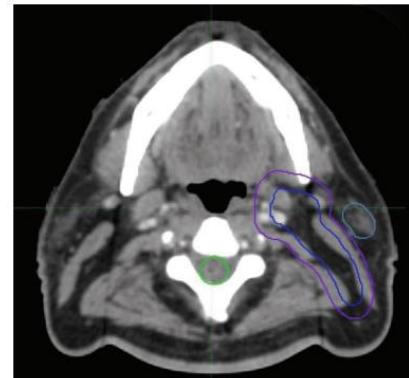
Radixact (Accuray)

kV range → good contrast resolution

Fan-beam

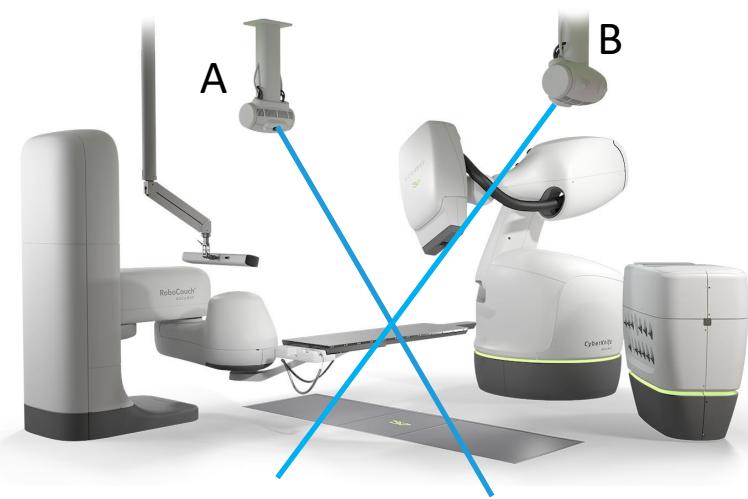


ClearRT™



Planning CT

# CyberKnife IGRT

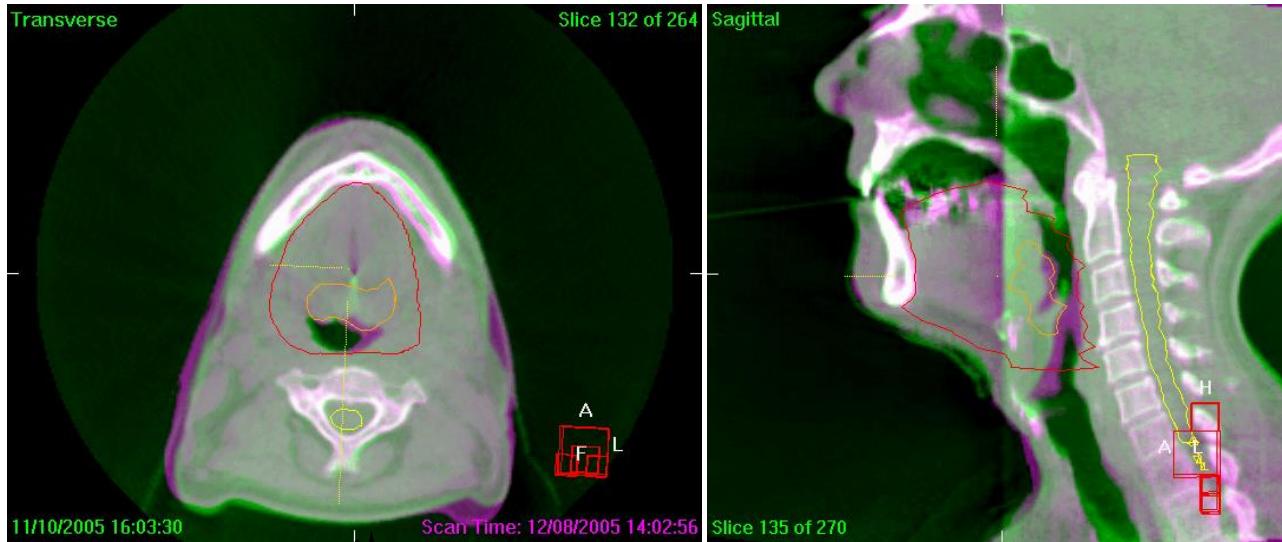


2 planar kV images

Comparison with DRR generated from planning CT



# Registration



Position Error	
Translation (cm)	
X	-0.25
Y	-0.05
Z	0.24
Rotation (dg)	
X	360.0
Y	2.5
Z	1.8



# Quality assurance (QA)

Recommendations No. 16

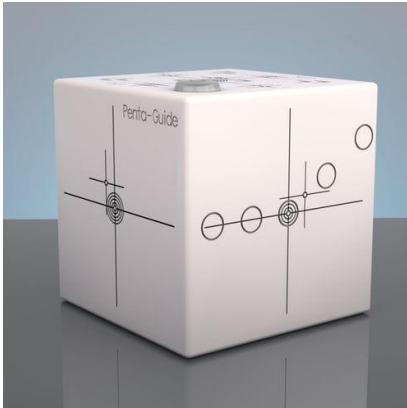
Chapter	Test	Frequency	Tolerance
2	<b>Safety</b>		
2.1.1	Interlocks	d	functional
2.1.2	Beam on indicators	w	functional
2.1.3	Anti-collision system	w	functional
3	<b>Geometric accuracy</b>		
3.1	kV Imaging field collimation	a	2 mm
3.2	Isocenter	d	2 mm
	Quick check	m	2 mm
3.3	Beam and panel alignment	a	1 °
3.4	Image registration and couch correction accuracy:	w	2 mm /1°
4	<b>Image performance</b>		
4.1	<b>Planar imaging</b>		
4.1.1	Spatial accuracy:	a	2 mm
4.1.2	Spatial resolution	a	kV: 1.6 lp/mm MV: 0.6 lp/mm
4.1.3	Contrast	a	kV: 3 % 8 mm Ø MV: 1.2 % 7 mm Ø
4.1.4	Noise /contrast-to-noise ratio	a	10 % baseline
4.1.5	Uniformity	a	10 % baseline
4.1.6	kV imaging dosimetry	a	20 % baseline
4.2	<b>CBCT imaging</b>		
4.2.1	Spatial accuracy:	a	2 mm
4.2.2	High contrast / spatial resolution	a	0.1 lp/mm
4.2.3	Contrast / Low contrast visibility	a	10 % baseline
4.2.4	Noise	a	10 % baseline
4.2.5	Uniformity	a	<2x baseline value
4.2.6	Sensitometry	a	Baseline
4.2.7	Slice thickness	a	50 % nominal
4.2.8	Artifacts	a	Absence
4.2.9	Imaging dosimetry	a	20 % baseline
5	<b>Data handling</b>		
5.1	Integrity	a	functional
5.2	Archiving and retrieving	a	functional

## SSRMP recommendation for QA of IGRT systems

1. Geometric accuracy
2. Image quality

# QA – Geometric accuracy

3	<b>Geometric accuracy</b>		
3.1	kV Imaging field collimation	a	2 mm
3.2	Isocenter      Quick check Full check:	d m	2 mm 2 mm
3.3	Beam and panel alignment	a	1 °
3.4	Image registration and couch correction accuracy:	w	2 mm /1°



**Geometric accuracy**

*Coincidence of imaging and treatment isocenters*

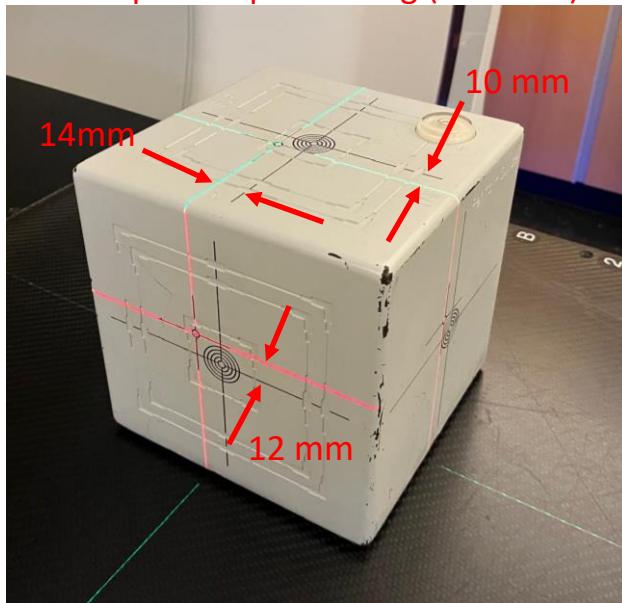
*Image registration accuracy*

*Couch correction accuracy*

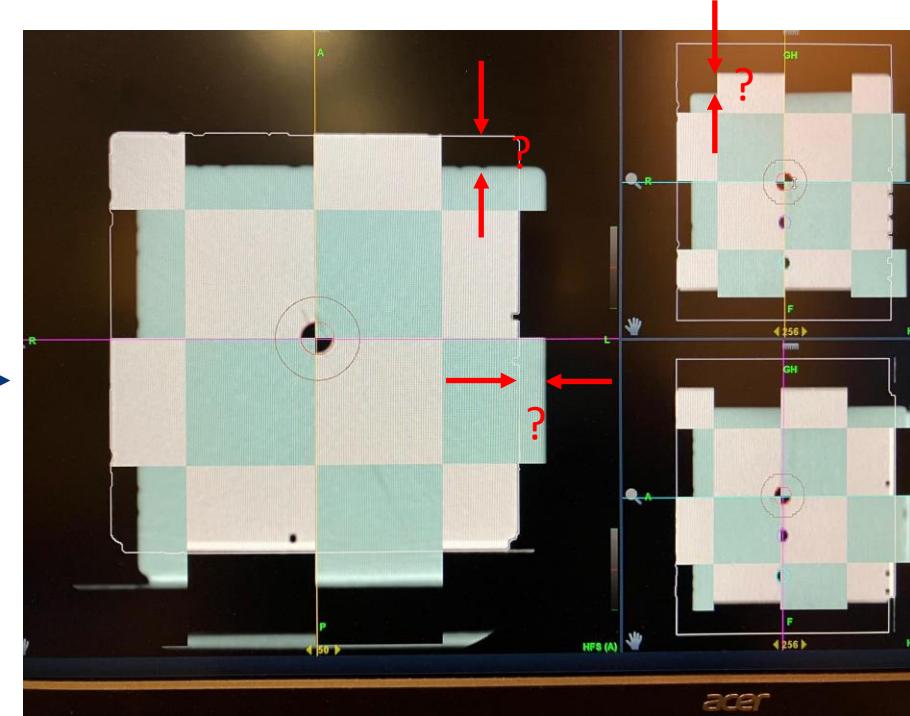
# QA – Geometric accuracy

Green laser = virtual machine isocenter (fixed)

Red laser = patient positioning (movable)

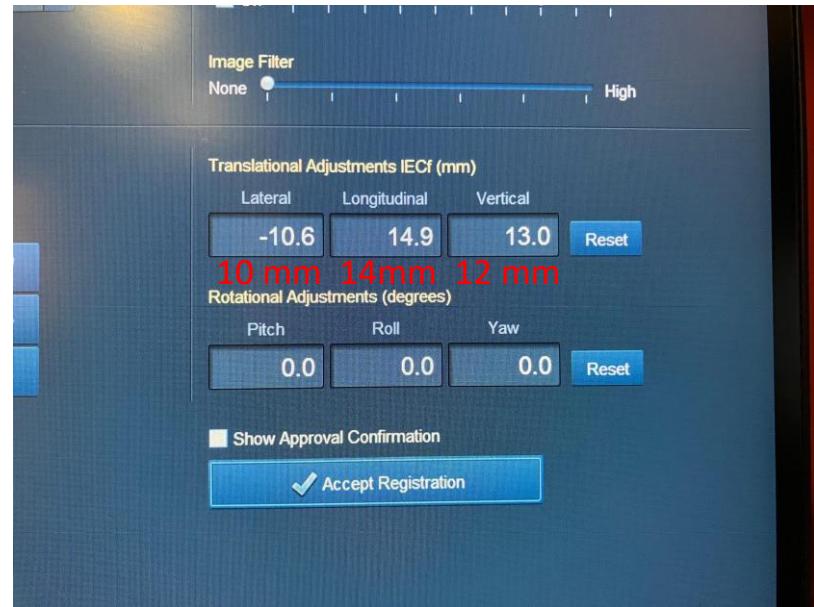
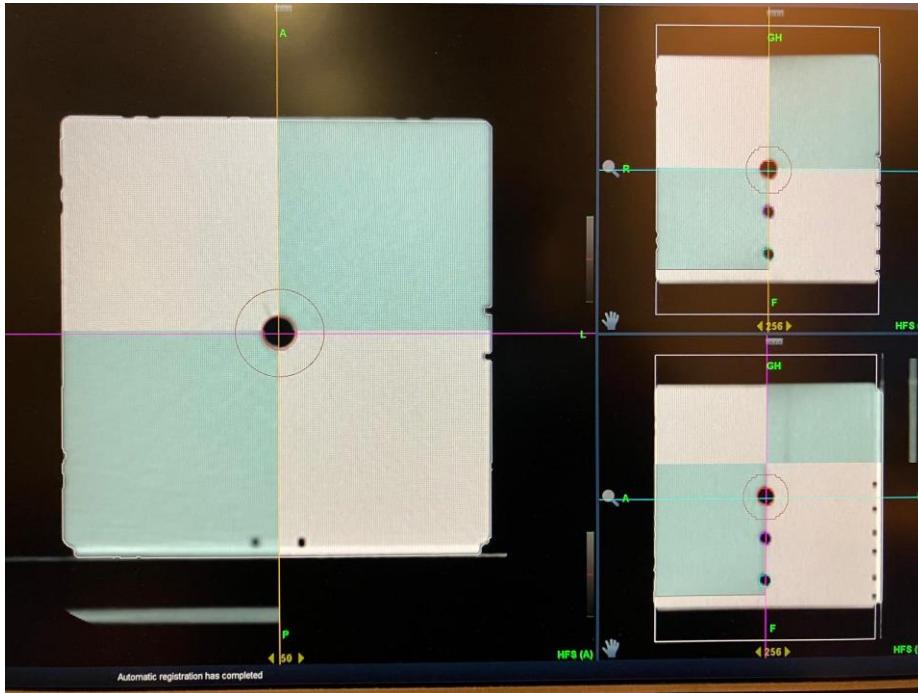


IMAGE



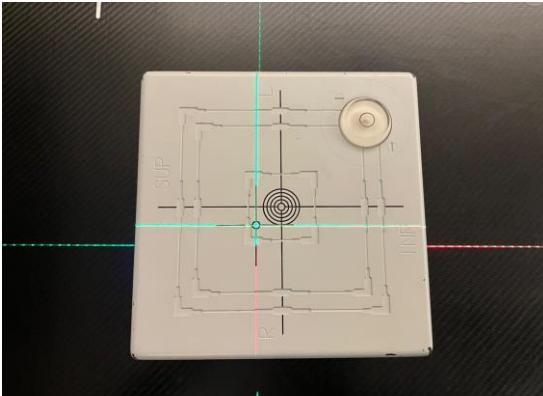
Pentaguide intentionally mispositioned  
Known offsets from the isocenter

# QA – Geometric accuracy

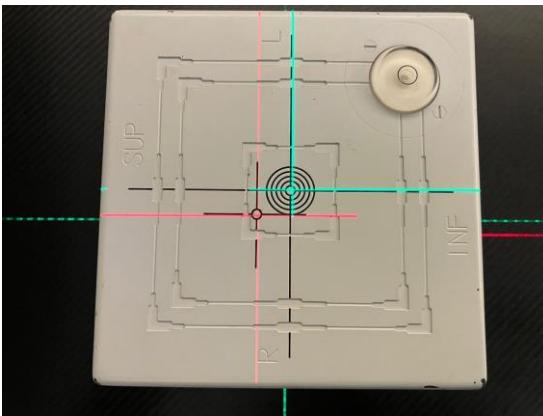


# QA – Geometric accuracy

Before



After



Offsets are applied to the couch  
→ Visual check

→ Registration accuracy  
→ Couch correction accuracy  
→ Coincidence of isocenters

# QA – Imaging quality/dose

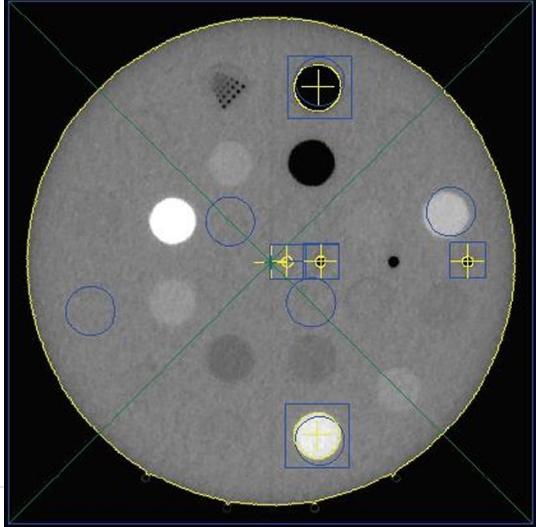


Image quality:

*Contrast*

*Noise*

*Uniformity*

*Spatial resolution*

*Distance accuracy*

Imaging dose

# Image quality parameters

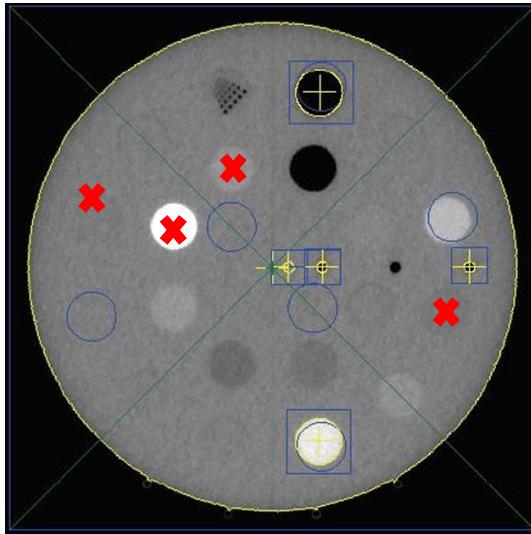


Image quality:  
Contrast

# Image quality parameters

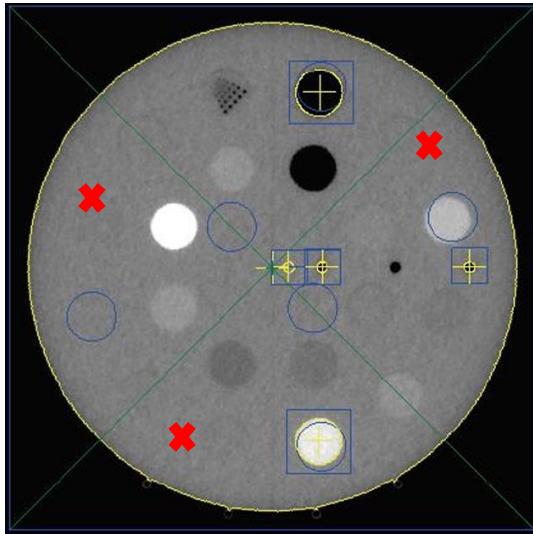


Image quality:

Contrast

Noise

# Image quality parameters

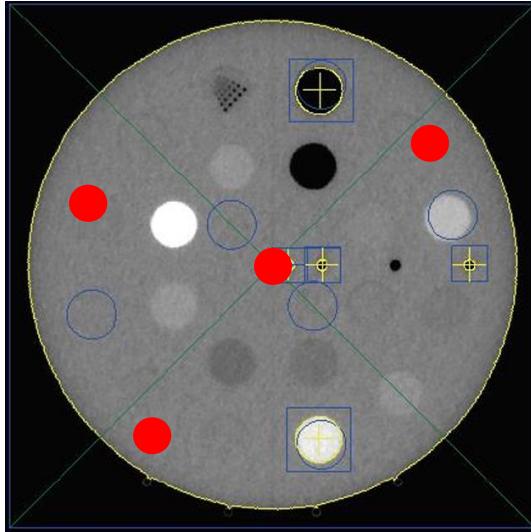


Image quality:

Contrast

Noise

Uniformity

# Image quality parameters

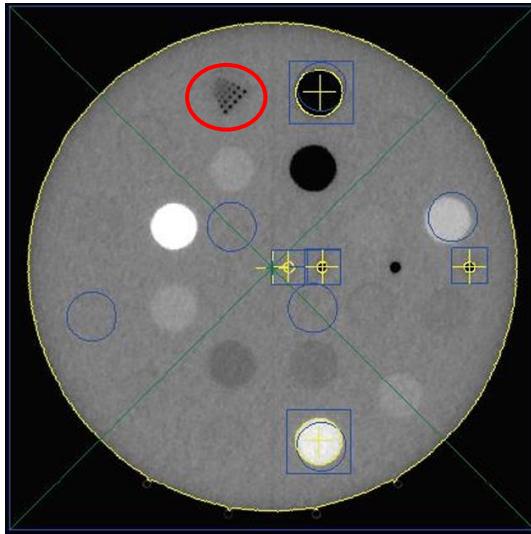


Image quality:

Contrast

Noise

Uniformity

Spatial resolution

# Imaging dose

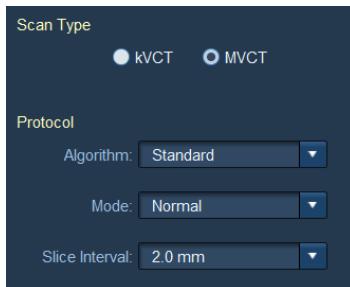


Image quality:  
Contrast  
Noise  
Uniformity  
Spatial resolution  
Imaging dose

Standard imaging procedure: 1.5 cGy

# Practical example: CyberKnife Tracking systems

# CyberKnife



# CyberKnife

Stereotactic treatments:

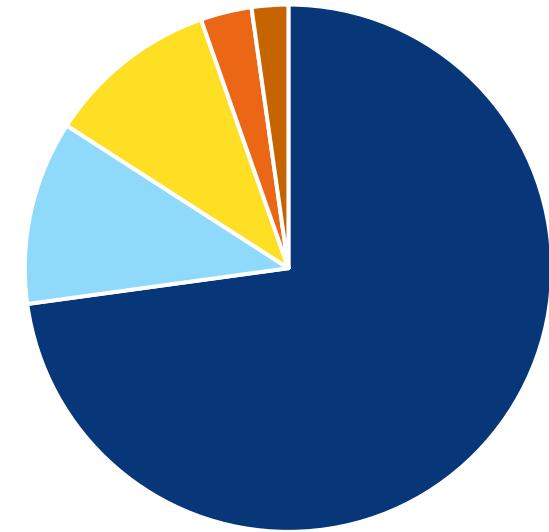
*High dose per fraction*

*Reduced number of fractions (1-5)*

*Small volumes/small fields*

*IGRT/tracking system*

*Brain, vertebra, lung*

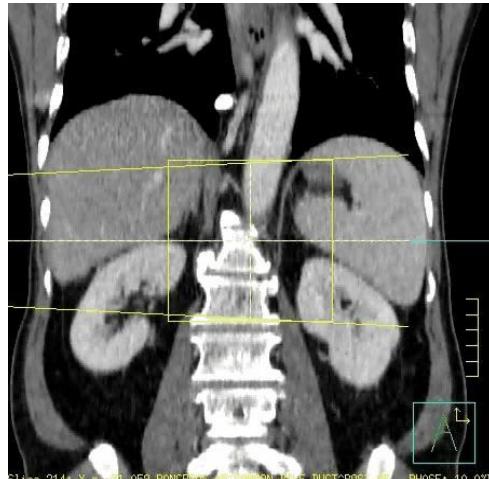
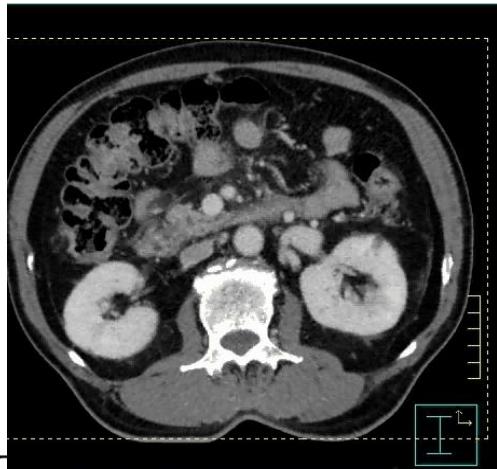


- Métastase Cérébrale
- Métastase Vertébrale
- Poumon
- Adénopathies
- Métastases Osseuses

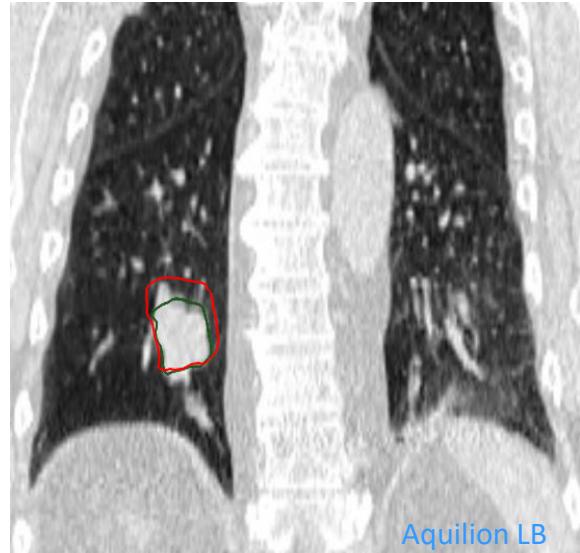
# CyberKnife

“high level” IGRT = Tracking (images also taken *during* the treatment)

→ Registration *before* and *during* the treatment fraction



Courtesy of Philips Medical Systems



# CyberKnife



3 collimator types:

*IRIS (12 diameters)*

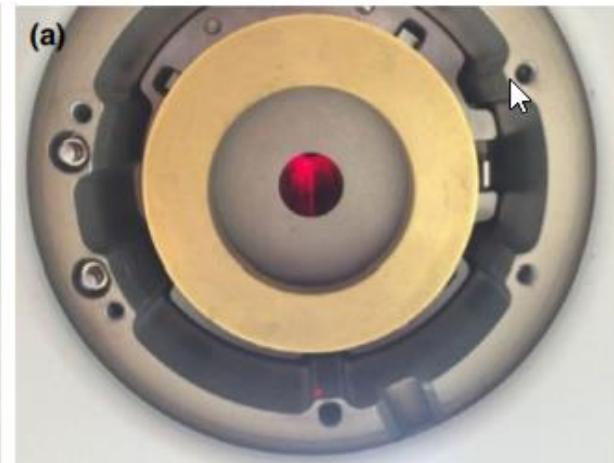
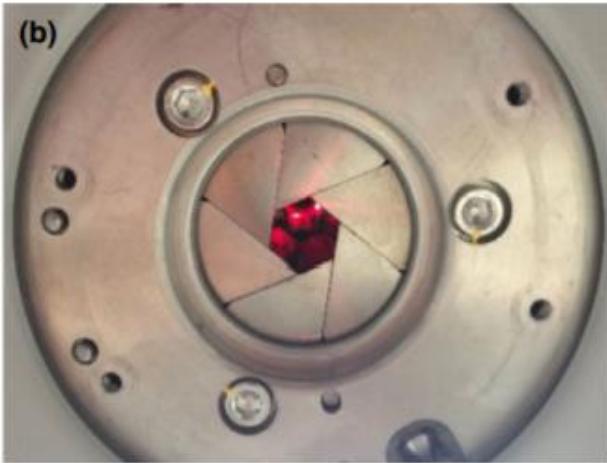
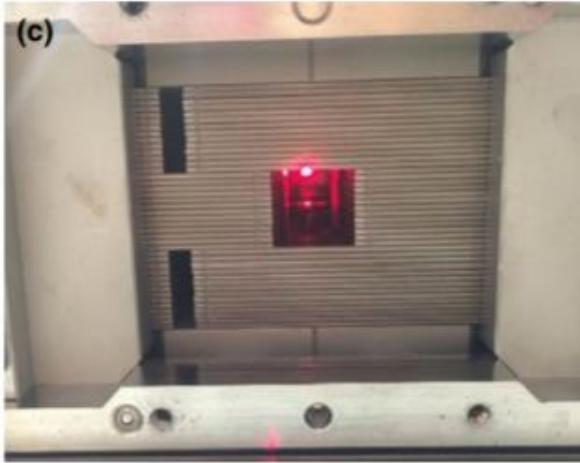
*Fixed (12 diameters)*

*MLC (max 10x11.5 cm<sup>2</sup>)*

Nominal energy

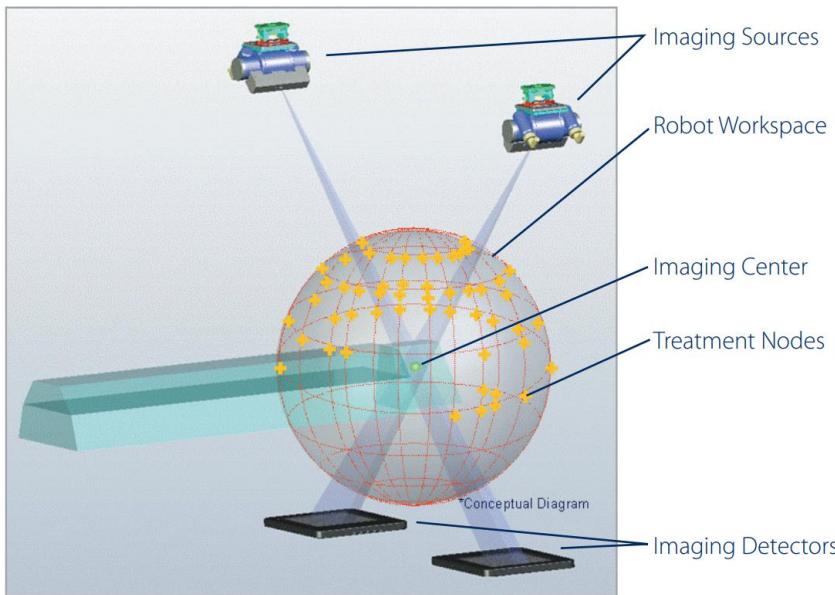
6 MV

# CyberKnife collimators



# CyberKnife

Robot Workspace



Imaging center

→ intersection of imaging beams

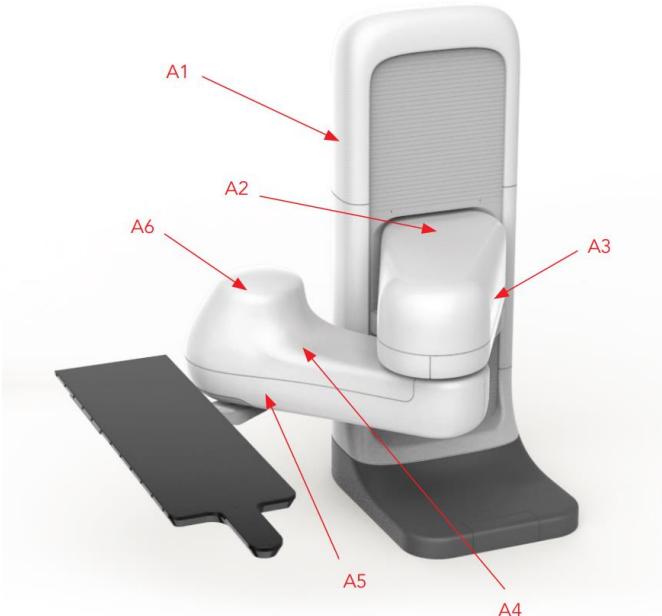
Nodes

→ possible robot positions defined on a sphere with imaging center as origin

# CyberKnife



# CyberKnife

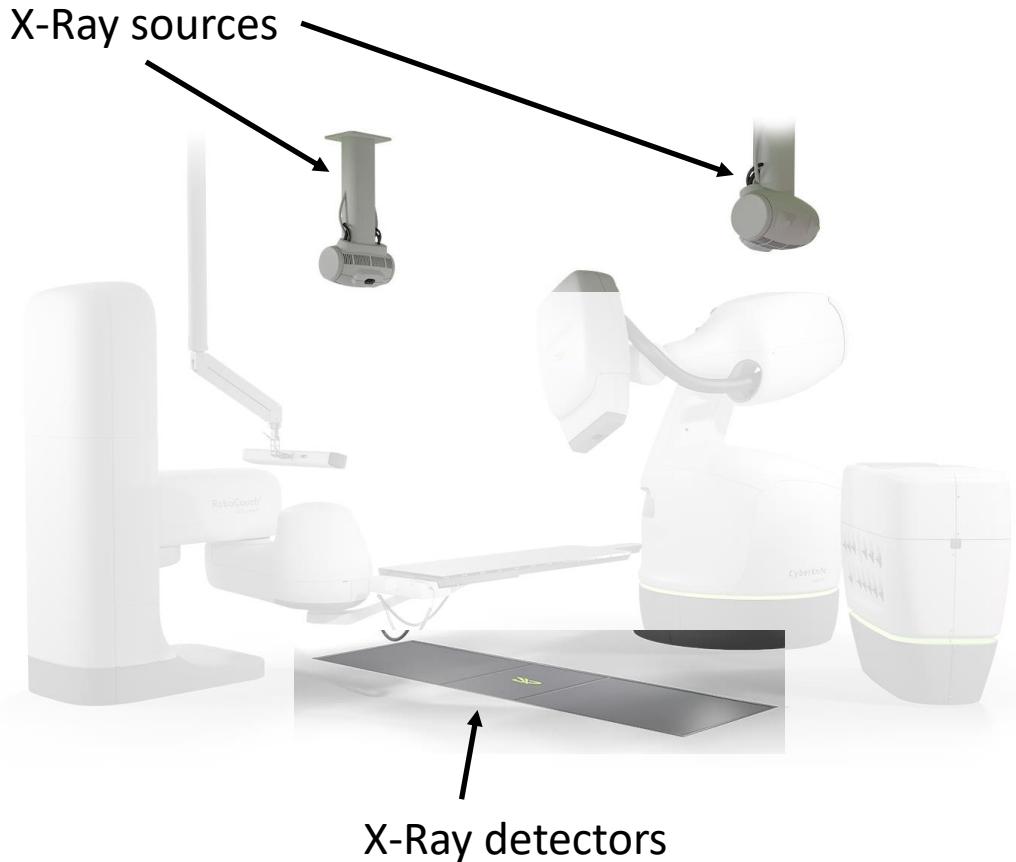


6 degrees of freedom Robocouch

*6 DoF : Corrections of translations and rotations*

*Initial patient positioning*

# CyberKnife



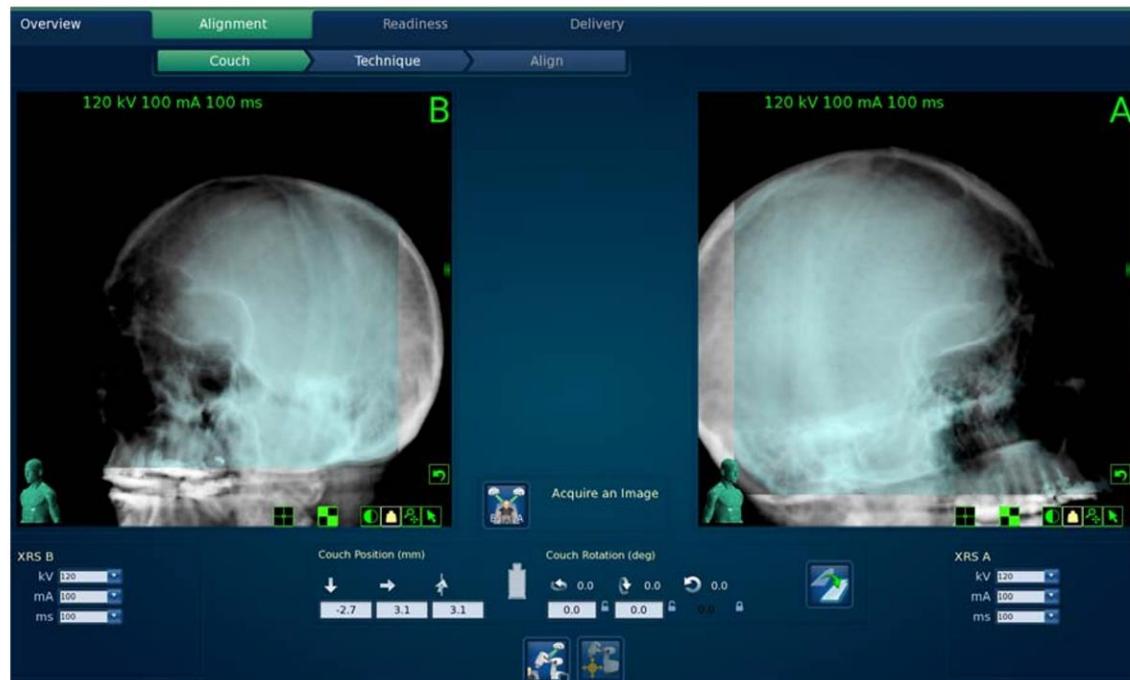
Imaging system

2 kV sources + detectors

# IGRT/Tracking : DRR comparison

Patient positioning *before* treatment (robocouch correction)

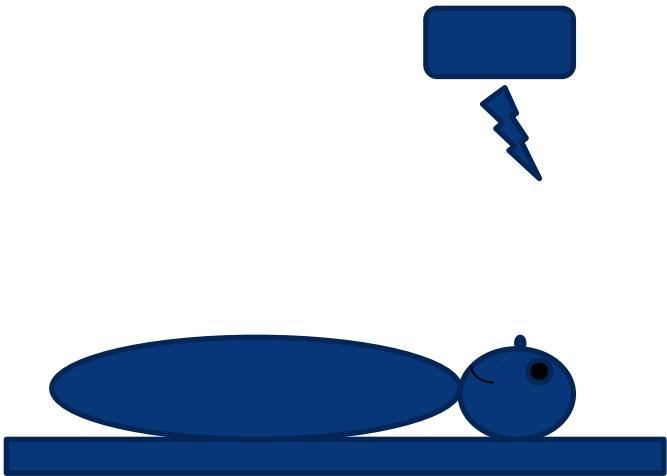
Tracking *during* treatment (robot correction)



# IGRT: before treatment start

IGRT: before beam on

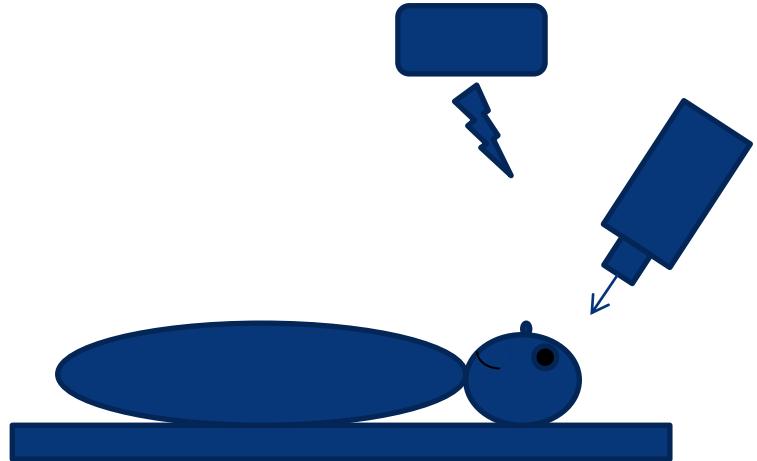
- Patient on couch
- kV imaging
- DRR comparison
- Couch correction



# Tracking: during treatment

Tracking: during beam *on*

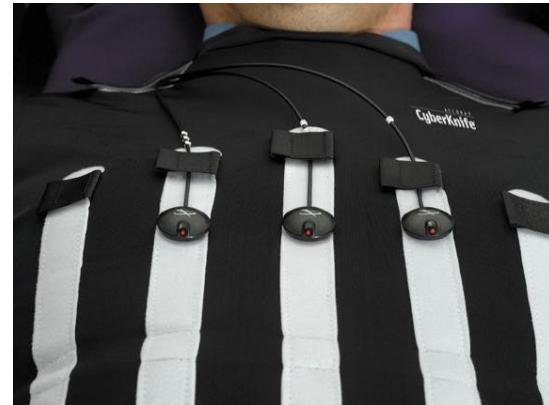
- kV imaging
- Automatic DRR registration
- Beam incidence (robot) correction



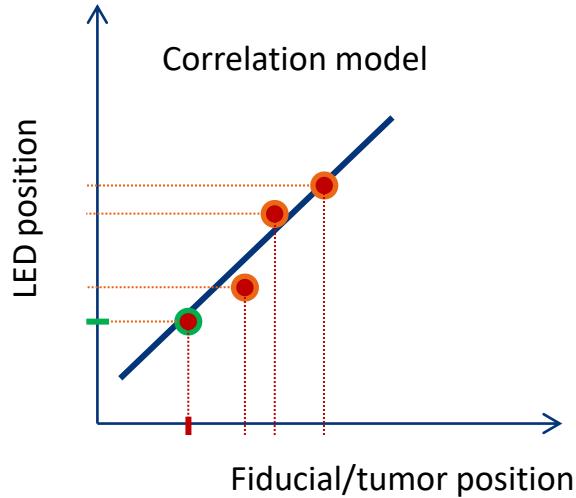
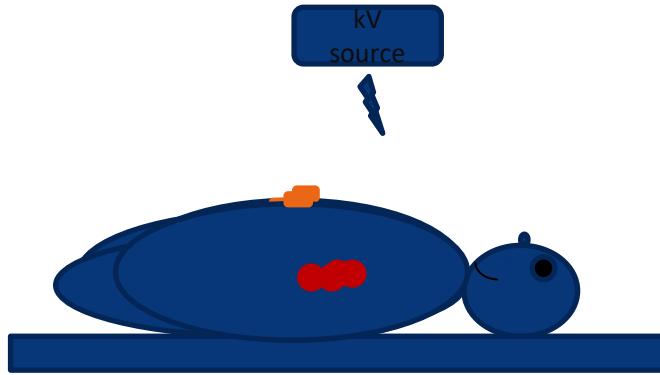
# Synchrony

Continuous synchronization between beam and tumor movement during breathing

*Correlation model* between patient's breathing pattern (real-time, LED) and movement of the target (fiducials, kV imaging)



# Synchrony: correlation model creation



1 image = 1 «external» respiratory position = 1 fiducial/tumor location  
Model updated during treatment  
Targeting accuracy < 1.5 mm